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P02-A-2	115	A Study on the Precise Distance Measurement for Radar Level Transmitter of FMCW Type using Correlation Analysis Method	Suk-Joon Ji, Hanla IMS Co.,Ltd ; Woo-Jin Choi, Hanla IMS Co.,Ltd; John-Tark Lee, Dong-A University; Kyung-Yup Kim, Hanla IMS Co., Ltd	
P03-A-2	195	Manual Asymmetry of Time-Delay Effect on Visual Feedback in Arm Movements	Takashi Oyama, Okayama Prefectural University	
P04-A-2	218	Reduction of Compressor Performance Test Duration Using Fuzzy-Bayesian Networks as Prediction Tool	Cesar Penz, Federal University of Santa Catarina; Carlos Flesch, Federal University of Santa Catarina; Rodolfo Flesch, Federal University of Santa Catarina; André Rosa, Whirpool SA	
P05-A-2	291	Distributed Scheduling Based Upon Frequency Transmission Using Two Dynamic Controlled Plants and a PID Controller	Oscar Esquivel, U.N.A.M.; Héctor Benítez, U.N.A.M.	
P06-A-2	296	The Implementation of Magnetostrictive Type Level Sensor System using Guided Pulse Wave	Woo-Jin Choi, Hanla IMS Co.,Ltd.; Suk-Joon Ji, Hanla IMS Co.,Ltd ; Kyung-Yup Kim, Hanla IMS Co., Ltd; John-Tark Lee, Dong-A University	
P07-A-2	427	Modeling and Implementation of Discrete Event Net Based Distributed Control for Industrial Robotic Systems	Gen'ichi Yasuda, Nagasaki Institute of Applied Science	
P08-A-2	438	Using Gyroscopic Sensors Data with Artificial Neural Networks for Junction Detection	Kenneth Mackin, Tokyo University of Information Sciences; Makoto Fujiyoshi, Hitachi Zosen Corporation	
P09-A-2	509	Tabu Search Based Topology Modification for Reduction of Fault Current Level in Power Systems	Manuel Del Castillo, Seoul National Univ of Science and Technology; Hwachang Song, Seoul National University of Science and Technology	
P10-A-2	529	Design of wind turbine fault detection system based on performance curve	Se-Yoon Kim, Kunsan National University; Sung-Ho Kim, Kunsan National University; In-Ho Ra, Kunsan National University	
P11-G-10	120	Identification of Longitudinal Dynamics of an Autonomous Small Scale Helicopter Using Hybrid Differential Evolution and Prediction Error Algorithm	Ari Legowo, International Islamic University Malaysia; Rini Akmeliawati, IIUM	
P12-G-10	245	Minimization of Accumulated Angular Error using Kalman Filter and Two Gyroscope	Jongguen Kim, Pusan National University; HaJun Song, Pusan National University; EunKook Jung, Pusan National University; Jungmin Kim, Pusan National University; Sungshin Kim, Pusan National University	
P13-G-10	493	Intelligent Platform Design of Agricultural Robot Inspired by Farmer Assistance (AGRIFA)	Young-Jae Ryoo, Mokpo National University; Ki-Nam Lee, Mokpo National University; Pil-Gong Choi, Mokpo National University	
P14-DKA-1	439	Self-localization based on Image Features of Omni-directional Image	Yasutake Takahashi, University of Fukui; Fuminori Hibino, University of Fukui; Yuta Ii, University of Fukui; Yoichiro Maeda, University of Fukui	
P15-JS-11	512	Stabilization and Walking Algorithm of Hybrid Wheeled and Legged Mobile Robot Based on ZMP	Dong-Hyuk Jeong, Hankyong National University; Yong-Tae Kim, Hankyong National University; Jong-Han Park, Hankyong National University; Bo-Hoon Lee, Hankyong National University	

P16-JS-11	535	Application of Particle Swarm Optimization to Humanoid Robot Walking	YoungLim Choi, Dong-A University; NakYoon Choi, Dong-A University; Jong-Wook Kim, Dong-A University	
P17-G-12	278	BUILDING AUTOMATION ONTOLOGICAL GENERATION OF INTELLECTUAL ELECTRONIC TEXTBOOKS	Assel Seifullina, L.N. Gumilyov Eurasian National University; Omarbekova Assel, L.N. Gumilyov Eurasian National University	
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P32-A-1	65	Interval-valued Evolution Strategy for Evolving Neural Networks with Interval Weights and Biases	Hidehiko Okada, Kyoto Sangyo University; Tetsuya Wada, Kyoto Sangyo University; Akira Yamashita, Kyoto Sangyo University; Takashi Matsuse, Kyoto Sangyo University	
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